AUX

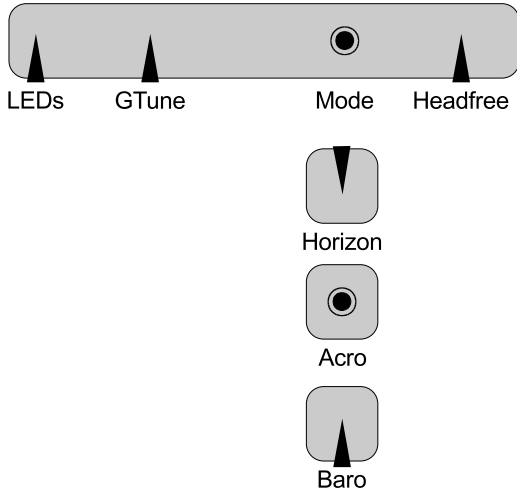LEDs   GTune   Mode   Headfree

Horizon

Acro

Baro

GTune

Arm
Enable G-tune
Lift off slowly
    Avoid stick inputs (Roll, Pitch / Yaw).
Eventually the copter should fly well.
    Perhaps do a few throttle punch outs
    Fly around a bit.
    Take note if each punch out seems to become
        smoother with less oscillation and the overall
        flight performance.
Disable G-tune
Land
Disarm, but don't power off.
If these are desired results
    Connect cleanflight configurator review and
        save the configuration.
     or
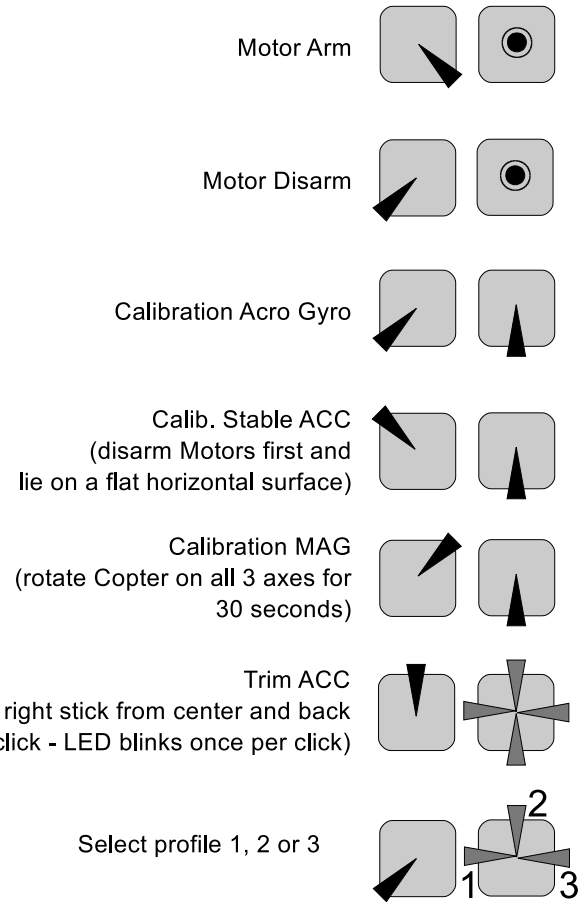   Enable G-Tune again to save settings.
Power off.

Modes

Acro: No Auto-level
The position of the control sticks on the TX control the rate of rotation around the relevant axis of the airframe. In this mode, there is no auto-level of any kind, and "centering the sticks" will simply cause the aircraft to maintain it's current attitude.

Horizon: Auto-level flight mode

Baro: Altitude hold mode (enables Horizon)

Head-free: Yaw has no effect on pitch/roll inputs
In this mode, the "head" of the multicopter is always pointing to the same direction as when the feature was activated. This means that when the multicopter rotates around the Z axis (yaw), the controls will always respond according the same "head" direction.

Commands

Motor Arm

Motor Disarm

Calibration Acro Gyro

Calib. Stable ACC
(disarm Motors first and
lie on a flat horizontal surface)

Calibration MAG
(rotate Copter on all 3 axes for
30 seconds)

Trim ACC
(move right stick from center and back
for each click - LED blinks once per click)

Select profile 1, 2 or 3

Profiles

Profile 1: Truc

Profile 2: Machin

Profile 3: Bidule